NRGC-ECAT





NRG controller with EtherCAT Communication





Main features

- Communication interface. The NRG controller bridges the field level devices to the control level to allow exchange of data in real-time with the NRG solid state relays.
- Reduced maintenance costs and downtime. Use of real-time data for prevention of machine stoppages during operation.
- Good quality products and low scrap rates. Real-time monitoring allows timely decisions for better machine and process management.
- Reduced efforts in troubleshooting. A number of faults can be distinguished to facilitate and reduce troubleshooting time.
- Fast installation and set-up. Control, monitoring and diagnostics all possible via the communication system.
- Compact dimensions. One controller with a product width of 35 mm can handle up to 32 RG..CM..N solid state relays.



Description

The NRGC-ECAT is the NRG controller in the NRG BUS chain.

The NRGC-ECAT interfaces directly with the main controller of the system through EtherCAT communication.

The **NRGC-ECAT** is mainly a facilitator of the communication between the main controller and each individual RG..N solid state relay in the system. The **NRGC-ECAT** also performs internal operations to setup and maintain the internal bus.

The **NRGC-ECAT** needs to be supplied with 24 VDC. LEDs on the front facade give a visual indication of the status of the **NRGC-ECAT**, of any ongoing communication with the main controller and the RG..Ns on the BUS chain and of any alarm condition related specifically to the **NRGC-ECAT**.

Specifications are noted at 25°C unless otherwise specified.



Applications

Any heating application where reliable and precise maintenance of temperatures is crucial to the quality of the end product. Typical applications include plastic machinery such as injection machines, extrusion machines and PET blow moulding machines, packaging machinery, sterilisation machinery, drying tunnels and semiconductor manufacturing equipment.

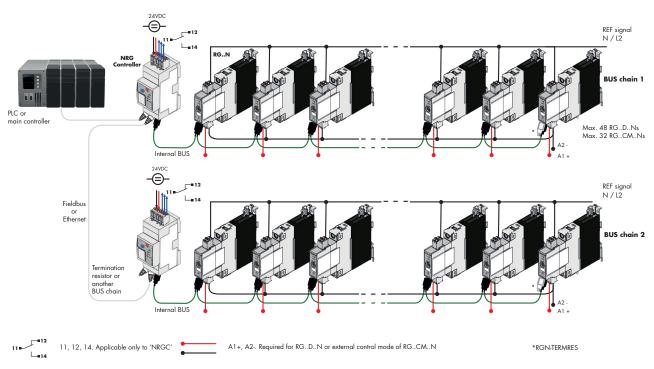


Main function

- Communication interface: EtherCAT
- Connects up to 32 RG..CM..Ns
- Supply voltage 24 VDC +/-20%



The NRG system





System Overview

The NRG is a system consisting of one or more BUS chains that enable communication between the field devices (such as the solid state relays) and the control devices (such as the machine controller or PLC).

Each NRG BUS chain consists of the following 3 components:

- · the NRG controller
- the NRG solid state relay(s)
- the NRG internal BUS cables

The **NRG controller** is the interface to the machine controller. It acts as the master of the BUS chain when performing specific actions on the respective BUS chain, and acts as a gateway for the communication between the PLC and the RG..N solid state relays. It is not possible to operate the NRG system without the NRG controller.

The NRG controllers available are:

NRGC

The NRGC is an NRG controller with a Modbus RTU interface over RS485. The NRGC is addressed via the assigned Modbus ID (from 1-247). In an NRG system operating on Modbus it is possible to have 247 NRG BUS chains.

NRGC-PN

NRGC-PN is an NRG controller with a PROFINET communication interface. The NRGC-PN is identified by a unique MAC address which is printed on the facade of the product. The GSD file can be downloaded from www. gavazziautomation.com

NRGC-EIP

NRGC-EIP is an NRG controller with an EtherNet/IP communication interface. The IP address is provided automatically via a DHCP server. The EDS file can be downloaded from www.gavazziautomation.com

NRGC-ECAT

NRGC-ECAT is an NRG controller with an EtherCAT communication interface. The ESI file can be downloaded from www.gavazziautomation.com





System Overview (continued)

The **NRG solid state relay** is the switching component in the NRG system. Each **RG..N** integrates a communication interface to exchange data with the machine controller (or PLC). The available RG..Ns that can be used in an NRG system are:

RG..D..N

The RG..D..N are solid state relays for use in an NRG system having the communication interface only for real time monitoring. Control of the RG..N is done via a DC control voltage. It is possible to have maximum 48 **RG..D..Ns** in one NRG BUS chain.

RG..CM..N

The RG..CM..N are solid state relays for use in an NRG system having a communication interface for control of the RG..N through the BUS and for real time monitoring. It is possible to have a maximum of 32 RG..CM..N in one NRG bus chain. There are two variants of the RG..CM..N:

RGx1A..CM..N - the solid state relay with zero cross switching

RGx1P..CM..N - the solid state relay with proportional switching.

For a review of the features available in both variants refer to the table below:

Feature	RGx1ACMN	RGx1PCMN
External control	•	-
ON / OFF switching	•	•
Burst switching	•	•
Distributed full cycle switching	•	•
Advanced full cycle switching	•	•
Phase angle	-	•
Soft start with time mode	-	•
Soft start with current limit mode	-	•
Voltage compensation	-	•
Monitoring of system parameters	•	•
SSR diagnostics	•	•
Load diagnostics	•	•
Overtemperature protection	•	•

It is not possible to mix RG..D..N and RG..CM..N in the same BUS chain.

The NRG internal BUS cables are proprietary cables that connect the NRG controller to the first RG..N in the NRG BUS chain and respective RG..Ns on the BUS. The internal BUS terminator, provided in the same package with the NRG controller, shall be plugged to the last RG..N in the NRG BUS chain.



NRG system required components

Description	Component code	Notes
Solid state relays	RGN	NRG solid state relays
NRG controller	NRGC	NRGC: NRG controller with Modbus RTU communication. NRGC-PN: NRG controller with PROFINET communication. NRGC-EIP: NRG controller with EtherNet/IP communication. NRGC-ECAT: NRG controller with EtherCAT communication RGN-TERMRES is included in the NRGC packaging. The RGN-TERMRES is to be mounted on the last RGN on the bus chain.
NRG internal BUS cables	RCRGN-xxx	Proprietary cables terminated at both ends with a micro USB connector

NRGC-ECAT



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References



Order code



NRGC-ECAT



Carlo Gavazzi compatible components

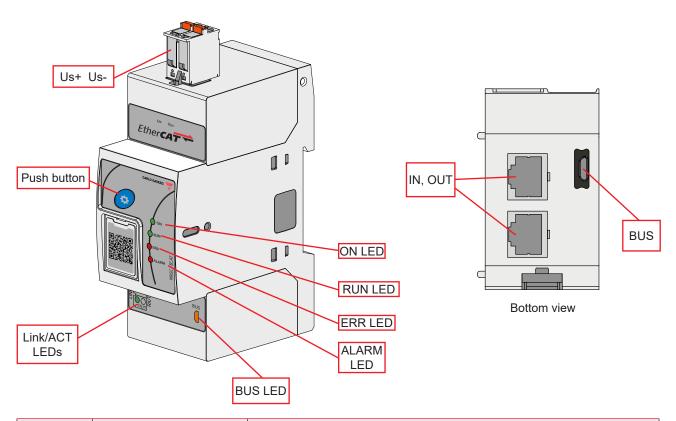
Description	Component code	Notes
Solid state relays	RGCMN	NRG solid state relays • RGCMN: Communication interface for control of the RGN and for real time monitoring. Maximum 32x RGCMN in one BUS chain.
NRG Internal BUS cables	RCRGN-010-2	10cm cable terminated at both ends with a microUSB connector. Packed x4 pcs.
	RCRGN-075-2	75cm cable terminated at both ends with a microUSB connector. Packed x1 pc.
	RCRGN-150-2	150cm cable terminated at both ends with a microUSB connector. Packed x1 pc.
	RCRGN-350-2	350cm cable terminated at both ends with a microUSB connector. Packed x1 pc.
	RCRGN-500-2	500cm cable terminated at both ends with a microUSB connector. Packed x1 pc.

Further reading

Information	Where to find it	
User manual NRG EtherCAT	https://gavazziautomation.com/images/PIM/MANUALS/ENG/SSR_UM_NRG_ECAT.pdf	
Datasheet RGCMN solid state relay with control and real time monitoring via bus	http://www.gavazziautomation.com/docs/mt_gh/SSR_RG_CM_N.pdf	
ESI file	https://gavazziautomation.com/images/PIM/OTHERSTUFF/ESI/ESI_NRGC-ECAT.zip	



Structure



Element	Component	Function
Us+ Us-	Supply connection	2 position spring plug – Us-, Us+ connection for powering the NRGC-ECAT
Push button	Communications check & Autoaddressing button	Enables and disables a Communications Check function of the BUS chain (link between NRGC-ECAT and RGNs) by pressing front button between 2 to 5 seconds Enables auto addressing of RGNs when pressed for 3 seconds during power up. Check 'Autoaddressing' section for more info.
ON LED	ON indicator	Indicates presence of supply voltage on NRGC-ECAT
BUS LED	BUS indicator	Indicates ongoing communication with RGNs
RUN LED	EtherCAT status	Status of EtherCAT State Machine
ERR LED	EtherCAT error	Indicates errors such as watchdog timeouts and unsolicited state changes
ALARM LED	ALARM indicator	Indicates presence of an alarm condition
Link / ACT LEDs	Link/Activity indicators	Indicates the status of the physical Ethernet connection
IN,OUT	Ethernet ports	2x RJ45 plugs for EtherCAT communication
BUS	Micro-USB port – internal BUS	RCRGN cable connection for the internal BUS communications line

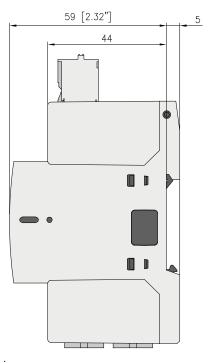


Features

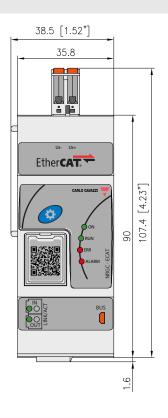
General data

Material	Noryl (UL94 V0), RAL7035
Mounting	DIN rail
Dimensions	2-DIN
Touch protection	IP20, IP00 with door flap on front facade open
Weight	142g
(Compatibility	RGCCMN solid state contactors (RG end-devices) RGSCMN solid state relays (RG end-devices)

Dimensions



All dimensions in mm. Tolerances +/- 0.5 mm.



Performance

Power supply specifications

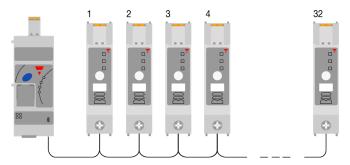
Supply port rating, Us	24 VDC
Supply voltage range, Us	19.2 – 32 VDC*
Reverse polarity protection	Yes
Consumption	< 12 W
LED Indication, Supply ON	Green LED
Power on	2 s

 $^{\star}\,$ to be supplied by class 2 power source according to UL1310



Auto-addressing

The RG..Ns on the bus chain are automatically addressed upon the first start-up of the system. The RG..Ns are addressed based on their position on the bus chain.



In case of an RG..N replacement, or any changes to the NRG bus chain, the RG..Ns have to be re-addressed. Follow the procedure below to re-address the RG..Ns on the NRG bus chain manually. Alternatively, auto-addressing can be done via an 'SDO' (check NRG EtherCAT User Manual for further information)



Fig. 1 Hold the blue button while powering up the NRGC-ECAT



Fig. 2 Release when Alarm LED turns ON indicating that autoaddressing is complete



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Communication

Communication protocol to Main Controller	EtherCAT	
ESI file	The ESI file for the NRGC-ECAT is available electronically by going to www.gavazziautomation.com	
Addressing	In an EtherCAT network, slave device addresses are assigned automatically	
Communication interface	The ethernet ports (IN,OUT) are 100 Mbit, full duplex operation ports and should be connected to another EtherCAT device with Cat5e (straight through) cable via the standard RJ45 connector. It is recomended that the interconnecting cables should be fitted with plugs provided with an outer metallic shell with the shell connected to the wire screen of the cable. For further information refer to the EtherCAT cabling guidelines	
LED indication - Link/ACT	Green, ON - Device is linked to Ethernet	

Internal Bus

Max. number of RGNs connected to NRGC-EIP	32x RGCMN
Connection to RGNs	RCRGN-xx 5-way cable terminated with micro-USB connection
BUS termination	RGN-TERMRES (1x pc. provided with 1x NRGC-ECAT) to be plugged on the last RGN on the BUS chain to terminate the internal BUS
LED indication - BUS	Yellow, ON indicating ongoing communication with the RG end-devices





Compatibility and Conformance

Approvals	CE LISTED EN CA
Standards compliance	LVD: EN 60947-5-1 / EE: BS EN 60947-5-1 EMCD: EN 60947-5-1 / EMC: BS EN 60947-5-1 UL: UL508, E172877, NMFT cUL: C22.2 No. 14-18, E172877, NMFT7

Electromagnetic compatibility (EMC) - Immunity		
Electrostatic discharge (ESD)	EN/IEC 61000-4-2 8 kV air discharge, 4 kV contact (PC1)	
Radiated radio frequency	EN/IEC 61000-4-3 10 V/m, from 80 MHz to 1 GHz (PC1) 10 V/m, from 1.4 to 2 GHz (PC1) 3 V/m, from 2 to 2.7 GHz (PC1)	
Electrical fast transient (burst)	EN/IEC 61000-4-4 Input: 1 kV, 5 kHz & 100 kHz (PC1) Internal bus: 1 kV, 5 kHz & 100 kHz (PC1) EtherCAT ports: 1 kV, 5 kHz & 100 kHz (PC1) 2 kV, 5 kHz & 100 kHz (PC2)	
Conducted radio frequency	EN/IEC 61000-4-6 10 V/m, from 0.15 to 80 MHz (PC1)	
Electrical surge	EN/IEC 61000-4-5 DC Output / Input, line to line: 500 V (PC2) DC Output / Input, line to earth: 500 V (PC2) Signal, line to earth 1 kV (PC2) ¹	
Voltage dips and interruptions	EN/IEC 61000-4-11 0% @ 5000 ms (PC2) 40% @ 200 ms (PC2) 60% @ 10, 30, 100, 300, 1000 ms (PC2)	
Voltage dips and interruptions on input lines	EN/IEC 61000-4-29 0% @ 1, 3, 10, 30, 100, 300, 1000 ms (PC2) 30% @ 10, 30, 100, 300, 1000 ms (PC2) 70% @ 10, 30, 100, 300, 1000 ms (PC2) 80% @ 10, 30, 100, 300, 1000 ms, 3 s, 10 s (PC2) 120% @ 10, 30, 100, 300, 1000 ms, 3 s, 10 s (PC2)	

^{1.} Not applicable to shielded cables <10m. Additional suppression on data lines may be required if shielded cables are not used.

Electromagnetic compatibility (EMC) - Emissions		
Radio interference field emission (radiated) EN/IEC 55011 Class A: from 30 to 1000 MHz		
Radio interference voltage emissions (conducted)	EN/IEC 55011 Class B: from 0.15 to 30 MHz	



Environmental specifications

Operating temperature	-20 to +65 °C (-4 to +149 °F)		
Storage temperature	-20 to +65 °C (-4 to +149 °F)		
Relative humidity	95% non-condensing @ 40°C		
Pollution degree	2		
Installation altitude	0 - 2000m		
EU RoHS compliant	Yes		
China RoHS			

LED indicators

	Green	ON:	Us is present at terminals Us+, Us-	
ON		OFF:	Us is not present at terminals Us+, Us-	
LINK / ACT	Green	ON:	Device is linked to Ethernet	
LINK / ACT		OFF:	Device has no link to Ethernet	
		ON:	During transmission of messages from NRGC-EIP to RGNs	
BUS	Yellow	OFF:	Idle bus between the NRGC-EIP and RGNs and when NRGC-EIP is receiving data from RGNs	
ALARM	Red	ON:	Flashing when alarm condition on NRGC-EIP is present. Refer to Alarm management section	
		OFF:	No alarm condition	
	Green	Green:	Operational: The device is in OPERATIONAL state	
RUN		Flickering:	Pre-Operational: The device is in PRE-OPERATIONAL state	
		Single Flash	Safe-Operational: The device is in SAFE-OPERATIONAL state	
		OFF:	INIT: The device is in INIT state	
	Red -	Flickering:	Invalid configuration: General Configuration error Possible reason: State change commanded by master is impossible due to register or object settings.	
		Double Flash	Application watchdog timeout: An application watchdog timeout has occurred. Possible reason: Sync Manager Watchdog timeout.	
ERR		Single Flash	Local error: Slave device application has changed the EtherCAT state autonomously. Possible reason 1: A host watchdog timeout has occurred. Possible reason 2: Synchronization error, device enters Safe-Operational automatically.	
		OFF:	No error: The EtherCAT communication of the device is in working condition	



Alarm management

Alarm condition present		ALARM LED ON with a specific flashing rate			
		Alarms are also available as process data via the EtherCAT communication interface. Refer to NRG EtherCAT User Manual for further information			
Alarm types	No. of flashes	Description of fault			
	2	 Errors in the configurations of the internal NRG bus chain including: Number of RGNs on bus chain is > 32 (Device Limit Error) More than one RGN on the bus chain have the same address (Device conflict error) One of the RGNs does not have an address. This may occur when a new RGN is introduced to the bus chain (Device Unconfigured Error) The internal Device ID of one of the RGNs on the bus chain does not correspond to its position on the bus (Device Position Error) 			
	4	Supply Error: Supply to NRGC-EIP is outside of the specified range			
	8	Communication Error (BUS): An error in the communication link (internal BUS) between the NRGC-ECAT and RGNs			
	9	Internal Error: Detection of internal issues with the NRGC-ECAT			
	10	Termination (BUS) Error: Internal BUS chain not terminated			
Flashing rate	0.5s →	<u>3s</u> <u> </u>			

Connection diagram

The NRG bus chain can be configured in a EtherCAT network via any network topology, the most favourable for EtherCAT networks are line and ring.

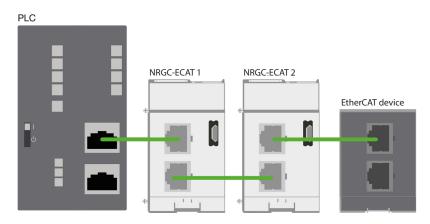
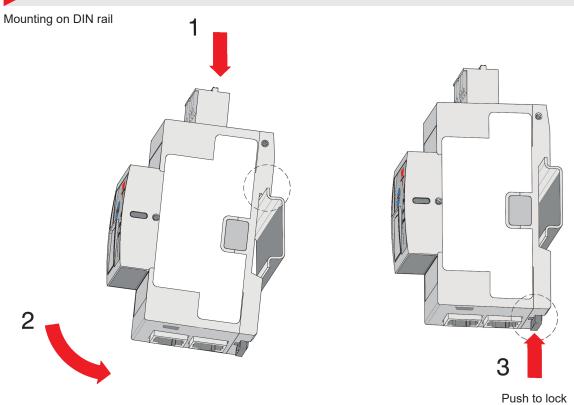
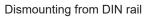


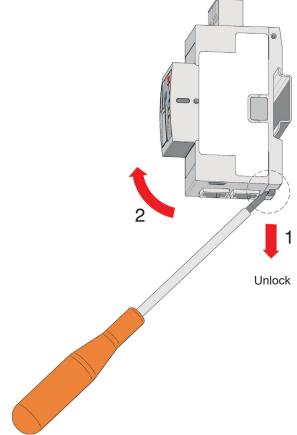
Fig. 3 Example of a line configuration of the NRGC-ECAT with other EtherCAT devices and controller



Mounting







RCRGN..



Connection specifications

Power connection		
Terminal	Supply: Us+, Us-	
	Top	
Conductors	Use 60/75°C copper (Cu) conductors	
Stripping length	12 - 13 mm	
Connection type	2-pole spring plug, pitch 5.08 mm	
Rigid (solid & stranded) UL/CSA rated data	0.2 – 2.5 mm², 26 – 12 AWG	
Flexible with end sleeve	0.25 – 2.5 mm ²	
Flexible without end sleeve	0.25 – 2.5 mm ²	
Flexible with end sleeve using TWIN ferrules	0.5 – 1.0 mm ²	

Communication - connection		
Terminal	X1, X2: RJ45 (x2) BUS: RCRGN-xxx-2	
	Bottom view	
EtherCAT connection	RJ45 shielded plugs	
Cable for EtherCAT	Not provided. Check EtherCAT cabling guidelines for further info.	
Max. length of Ethernet cable	100 mtrs (between EtherCAT devices)	
Cable for Internal Bus	RCRGN-xxx-2: 5-way USB micro connection - +24 supply line for RGNs - GND - RS485A - RS485B - Autoconfig / Auto addressing line	



NRG internal BUS cable



Main features

- Cables available at various lengths to provide the internal BUS of the NRG system
- Cables terminated at both ends with a microUSB plug
- Connects the NRG controller to the RG..N solid state relay and respective RG..N solid state relays

Description

The **RCRGN** cables are proprietary cables that must be used with the NRG system for the internal BUS. These cables connect the NRG controller to the RG..N solid state relays and respective RG..N solid state relays.

The RCRGN... are 5-way cables carrying the communication, supply and autoconfiguration / auto-addressing lines. By means of autoconfiguration / auto-addressing, the RG..Ns are assigned a unique ID based on the physical location and on the internal BUS.

Carlo Gavazzi compatible components

Description	Component code	Notes
NRG Controller	NRGC	 NRGC: NRG controller with Modbus communication. NRGC-PN: NRG controller with PROFINET communication. NRGC-EIP: NRG controller with EtherNet/IP communication. NRGC-ECAT: NRG controller with EtherCAT communication. 1x RGN-TERMRES is included in the NRGC packaging. The RGN-TERMRES is to be mounted on the last RGN on the bus chain.
Solid state relays	RGN	NRG solid state relays

Order code



Enter the code entering the corresponding option instead of lacksquare

Code	Option	Description	Notes	
R		Cables		
С		Cables		
R				
G	-	Suitable for the NRG system		
N				
	010	10 cm cable length	packed x 4 pcs.	
	075	75 cm cable length	packed x 1 pc.	
	150	150 cm cable length	packed x 1 pc.	
	350	350 cm cable length	packed x 1 pc.	
	500	500 cm cable length	packed x 1 pc.	
2	-	Terminated at the both ends with a microUSB connector		





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